

Algorithms - Fall 2020

Flows
(final day?)



Recap

- HW due Saturday
caution: I'm often busy
Sunday.
- Reading as usual.
- Next HW - probably
oral grading

Max flow/Min Cut:

- FF: $O((V+E) \underline{f^*})$
- Edmonds-Karp: $O(E^2 \log E \log \underline{f^*})$
- BFS based: $O(VE^2)$ (no f^*)

based on G

Technique	Direct	With dynamic trees	Source(s)
<u>Blocking flow</u>	$O(V^2E)$	$O(VE \log V)$	[Dinitz; Karzanov; Even and Itai; Sleator and Tarjan]
<u>Network simplex</u>	$O(V^2E)$	$O(VE \log V)$	[Dantzig; Goldfarb and Hao; Goldberg, Grigoriadis, and Tarjan]
Push-relabel (generic)	$O(V^2E)$	—	[Goldberg and Tarjan]
Push-relabel (FIFO)	$O(V^3)$	$O(VE \log(V^2/E))$	[Goldberg and Tarjan]
Push-relabel (highest label)	$O(V^2\sqrt{E})$	—	[Cheriyani and Maheshwari; Tunçel]
Push-relabel-add games	—	$O(VE \log_{E/(V \log V)} V)$	[Cheriyani and Hagerup; King, Rao, and Tarjan]
Pseudoflow	$O(V^2E)$	$O(VE \log V)$	[Hochbaum]
Pseudoflow (highest label)	$O(V^3)$	$O(VE \log(V^2/E))$	[Hochbaum and Orlin]
Incremental BFS	$O(V^2E)$	$O(VE \log(V^2/E))$	[Goldberg, Held, Kaplan, Tarjan, and Werneck]
<u>Compact networks</u>	—	$O(VE)$	[Orlin]

??

Figure 10.10. Several purely combinatorial maximum-flow algorithms and their running times.

Many use very different techniques

- linear programming
- complex data structures
- not residual graphs

Still active!

8:46 AM Mon Oct 26

arxiv.org

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1. [arXiv:2009.03260](#) [[pdf](#), [ps](#), [other](#)] [cs.DS](#) [math.OC](#)

A Potential Reduction Inspired **Algorithm** for Exact **Max Flow** in Almost $\tilde{O}(m^{4/3})$ Time

Authors: [Tarun Kathuria](#)

Abstract: We present an algorithm for computing s - t maximum flows in directed graphs in $\tilde{O}(m^{4/3+o(1)}U^{1/3})$ time. Our algorithm is inspired by potential reduction interior point methods for linear programming. Instead of using scaled gradient/Newton steps of a potential function, we take the step which maximizes the step size in the potential value subject to advancing a certain amount α . [More](#)
Submitted 7 September, 2020; **originally announced** September 2020.

2. [arXiv:1910.04848](#) [[pdf](#), [other](#)] [cs.DS](#) [cs.CC](#)

A Fast **Max Flow Algorithm**

Authors: [James B. Orlin](#), [Xiao-Yue Gong](#)

Abstract: In 2013, Orlin proved that the max flow problem could be solved in $O(nm)$ time. His algorithm ran in $O(nm + m^{1.94})$ time, which was the fastest for graphs with fewer than $n^{1.06}$ arcs. If the graph was not sufficiently sparse, the fastest running time was an algorithm due to King, Rao, and Tarjan. We describe a new variant of the **exact** scaling algorithm for the max flow problem whose runn... [More](#)
Submitted 10 October, 2019; **originally announced** October 2019.
Comments: 35 pages

3. [arXiv:1901.01412](#) [[pdf](#), [other](#)] [cs.DS](#)

New **Algorithms** and Lower Bounds for All-Pairs **Max-Flow** in Undirected Graphs

Authors: [Amir Abboud](#), [Robert Krauthgamer](#), [Ohad Trabelsi](#)

Abstract: We investigate the time-complexity of the All-Pairs Max-Flow problem: Given a graph with n nodes and m edges, compute for all pairs of nodes the maximum-flow value between them. If Max-Flow (the version with a given source-sink pair s, t) can be solved in time $T(m)$, then an $O(n^2) \cdot T(m)$ is a trivial upper bound. But can we do better? For directed graphs, recent results in fine-grai... [More](#)
Submitted 9 July, 2019; v1 submitted 5 January, 2019; **originally announced** January 2019.

4. [arXiv:1304.2338](#) [[pdf](#), [other](#)] [cs.DS](#)

An Almost-Linear-Time **Algorithm** for Approximate **Max Flow** in Undirected Graphs, and its Multicommodity Generalizations

Authors: [Jonathan A. Kelner](#), [Yin Tat Lee](#), [Lorenzo Orecchia](#), [Aaron Sidford](#)

Abstract: In this paper, we introduce a new framework for approximately solving flow problems in capacitated, undirected graphs and apply it to provide asymptotically faster algorithms for the maximum s - t flow and maximum concurrent multicommodity flow problems. For graphs with n vertices and m edges, it allows us to find an ϵ -approximate maximum s - t flow in time $O(m^{1+o(1)}\epsilon^{-2})$, improvi... [More](#)
Submitted 23 September, 2013; v1 submitted 8 April, 2013; **originally announced** April 2013.

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"special" graphs:

Computer Science > Data Structures and Algorithms

Minimum Cuts in Surface Graphs

[Erin W. Chambers](#), [Jeff Erickson](#), [Kyle Fox](#), [Amir Nayyeri](#)

(Submitted on 9 Oct 2019)

We describe algorithms to efficiently compute minimum (s, t) -cuts and global minimum cuts of undirected surface-embedded graphs. Given an edge-weighted undirected graph G with n vertices embedded on an orientable surface of genus g , our algorithms can solve either problem in $g^{O(g)}n \log \log n$ or $2^{O(g)}n \log n$ time, whichever is better. When g is a constant, our $g^{O(g)}n \log \log n$ time algorithms match the best running times known for computing minimum cuts in planar graphs.

Our algorithms for minimum cuts rely on reductions to the problem of finding a minimum-weight subgraph in a given $\mathbb{Z}_2$ -homology class, and we give efficient algorithms for this latter problem as well. If G is embedded on a surface with b boundary components, these algorithms run in $(g + b)^{O(g+b)}n \log \log n$ and $2^{O(g+b)}n \log n$ time. We also prove that finding a minimum-weight subgraph homologous to a single input cycle is NP-hard, showing it is likely impossible to improve upon the exponential dependencies on g for this latter problem.

Topics in Ch. 11

A mess of different ideas!

① Matchings:

~~✗~~ Identify a way to pair up items. } no G in this!

Build G' : More pairs $\Leftrightarrow$ larger flow

② Disjoint paths:

~~Modify G:~~ use flow

Find paths that avoid each other.

③ "Tuple" Selection

~~✗~~ Build a graph: flow paths
give selection

Magic:

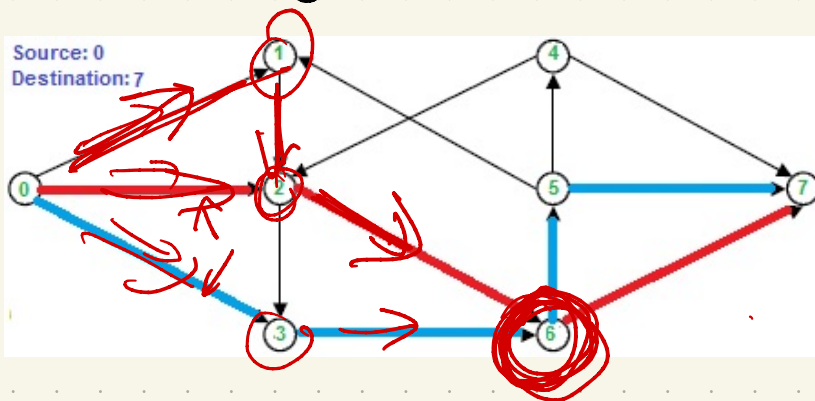
Flows/cuts solve a lot of problems!

First problem

What if we want non-intersecting paths from s to t ?

Two variants:

- Edge disjoint: No 2 paths visit the same edge



2 - only 1 vertex disjoint path

- Vertex disjoint: no 2 paths visit the same vertex
Stricter!

Note: Different! And both model useful cases.

Key: Flow will decompose into paths!
 $f(e)/c(e)$
in Chlo

Edge disjoint:

Input: unweighted graph G , src

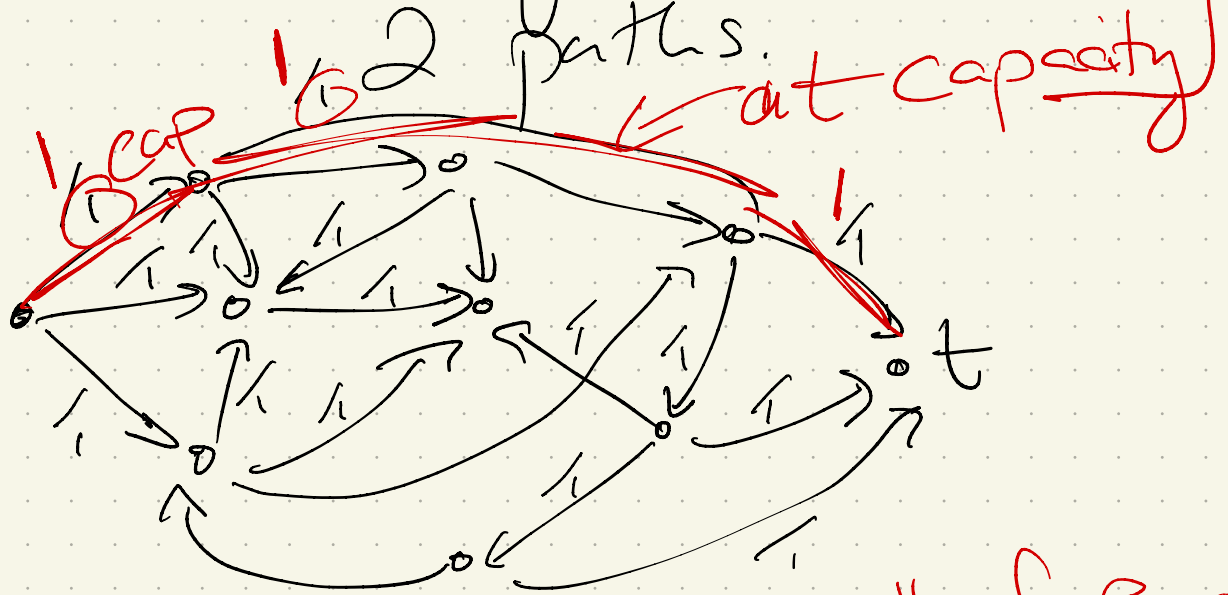
Goal: Compute max # of e-d, src paths

$\hat{G}$: Simply add capacity = 1 to each edge.

Run max flow, + ~~trace~~ decompose into paths from $s \rightarrow t$.

Since all flows are integral,
+ capacity of every edge
is = 1

$\Rightarrow$ no edge will be in 2 paths.

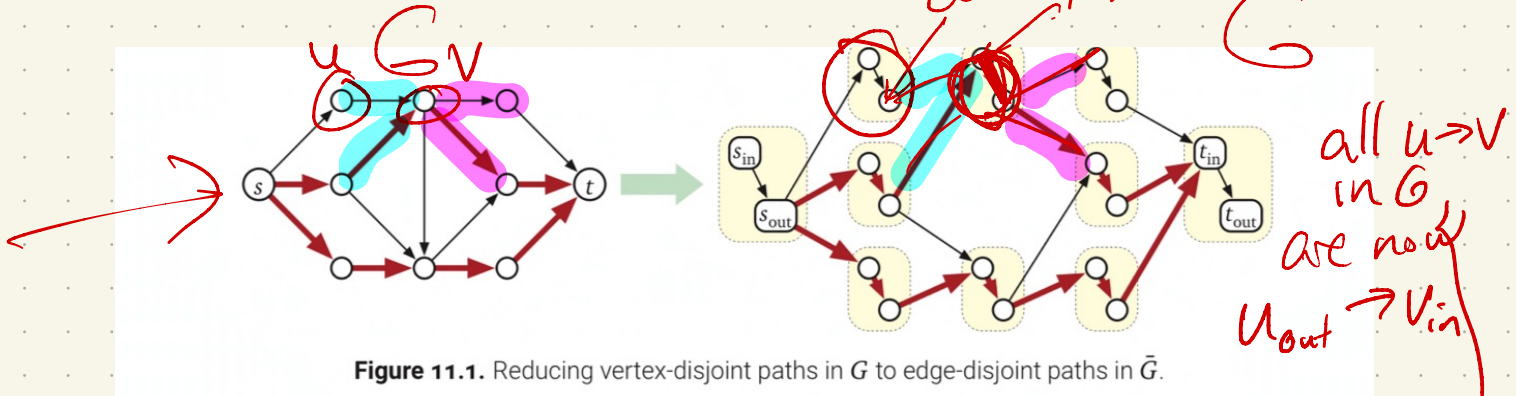


max flow $\Leftrightarrow$ max # of e-d paths

Vertex disjoint:

Build a new graph

$\tilde{G}$



$$V(\tilde{G}) = \text{vert. of } \tilde{G} = 2 \times V(G)$$

$$E(\tilde{G}) = \text{edge of } \tilde{G} = \text{edges of } G + \text{edge b/t } v_{in} \text{ \& } v_{out}$$

Add capacity = 1 to each edge. Run max flow alg($\tilde{G}$)

Any flow path that enters v_{in} will exit v_{out} , so $f(v_{in} \rightarrow v_{out}) = 1 = C(v_{in} \rightarrow v_{out})$ only 1 out edge to v_{out}

Result: each vertex appears in only 1 flow path

Another (his) variant

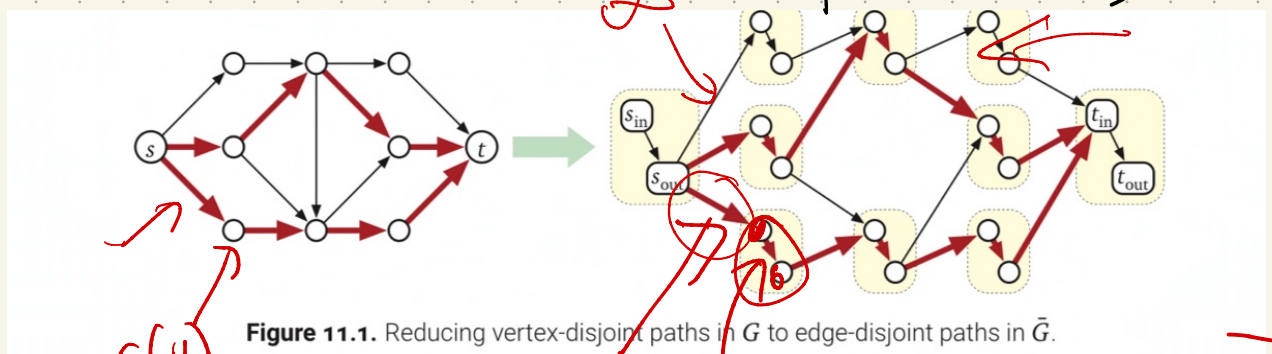
Suppose edges are unlimited,
but vertices have capacities.

Ex: Internet routing:
packets queue up at
routers/switches

So: $G = (V, E)$ & $c(v)$ give
capacities on vertices

How to do flow?

Build $\bar{G}$ (with only edge
capacities)



capacity ∞

give capacity
 $= c(v)$ in G

Correctness

max flow in G (not exceeding vertex capacities)
 $\Rightarrow$ max flow in $\tilde{G}$

∞ edges in $\tilde{G}$ are fine
in G flow, no vertex is
exceeded $\rightarrow$ in $\tilde{G}$, $V_{in} \rightarrow V_{out}$
edges are also $\leq Cap$.

max flow in $\tilde{G}$

$\Rightarrow$ max flow in G

∞ edges are same
vertex capacities same
as $V_{in} \rightarrow V_{out}$

So: compute in $\tilde{G}$ (but input was G)
On/in

Runtime: $O(V(\tilde{G}) \times E(\tilde{G}))$

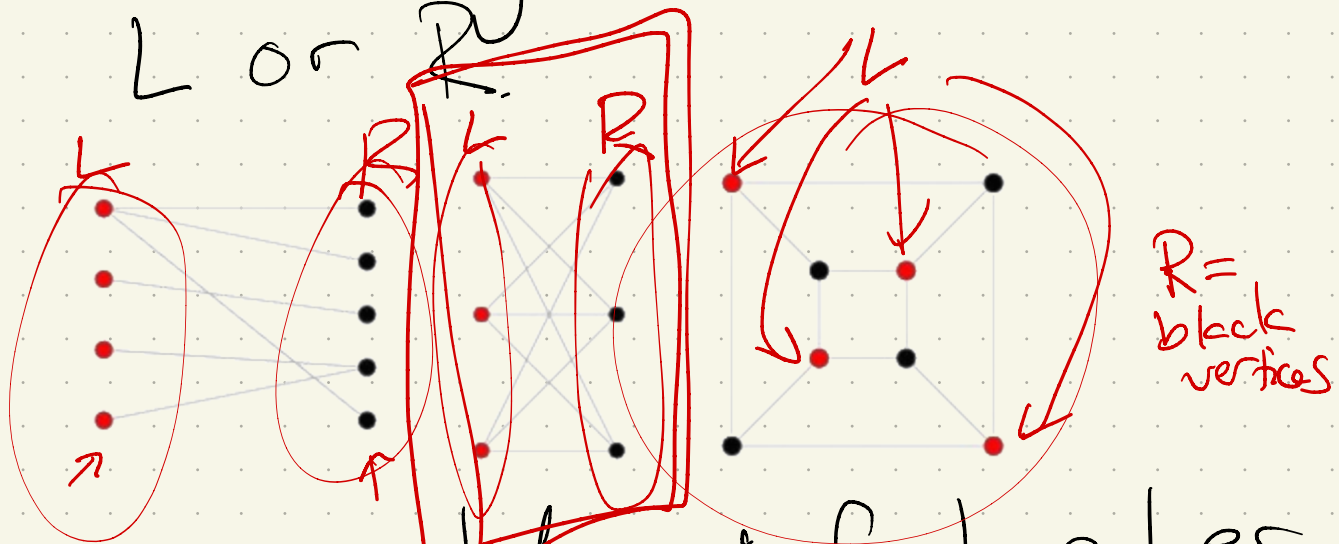
$$O(V^2 + VE) = O([2 \cdot V(G)] \times [E(G) + V(G)])$$

Bipartite Graphs

Any graph where vertices can be divided into 2 sets
(usually L & R)

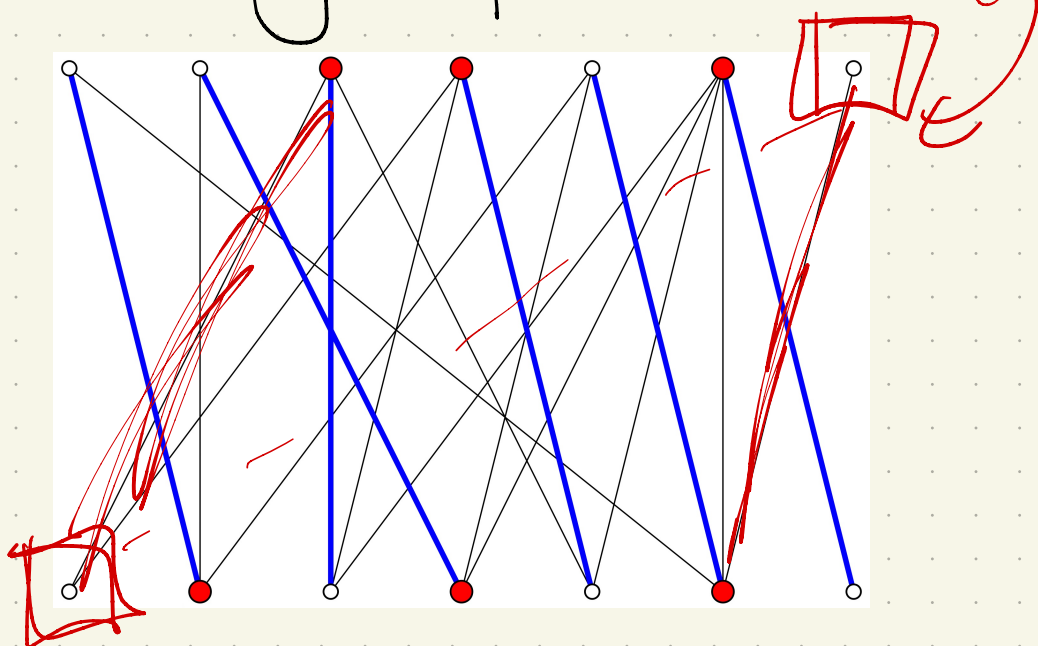
s.t. no edges exist inside
 L or R .

Ex:



Maximum matching: find edges
(no 2 edges per vertex)

ex:
doctors
& hospitals



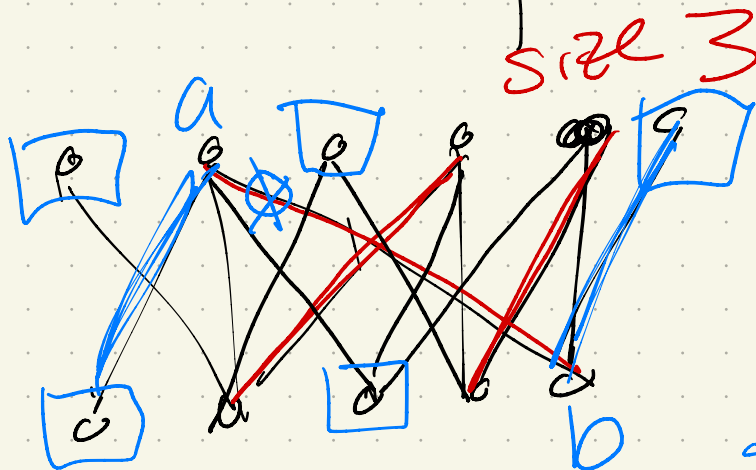
How to compute?

Greedy ideas:

- match vertex with minimum degree first
↳ fails
gives a matching but not largest

Iterative improvement: ~~X~~ use flow

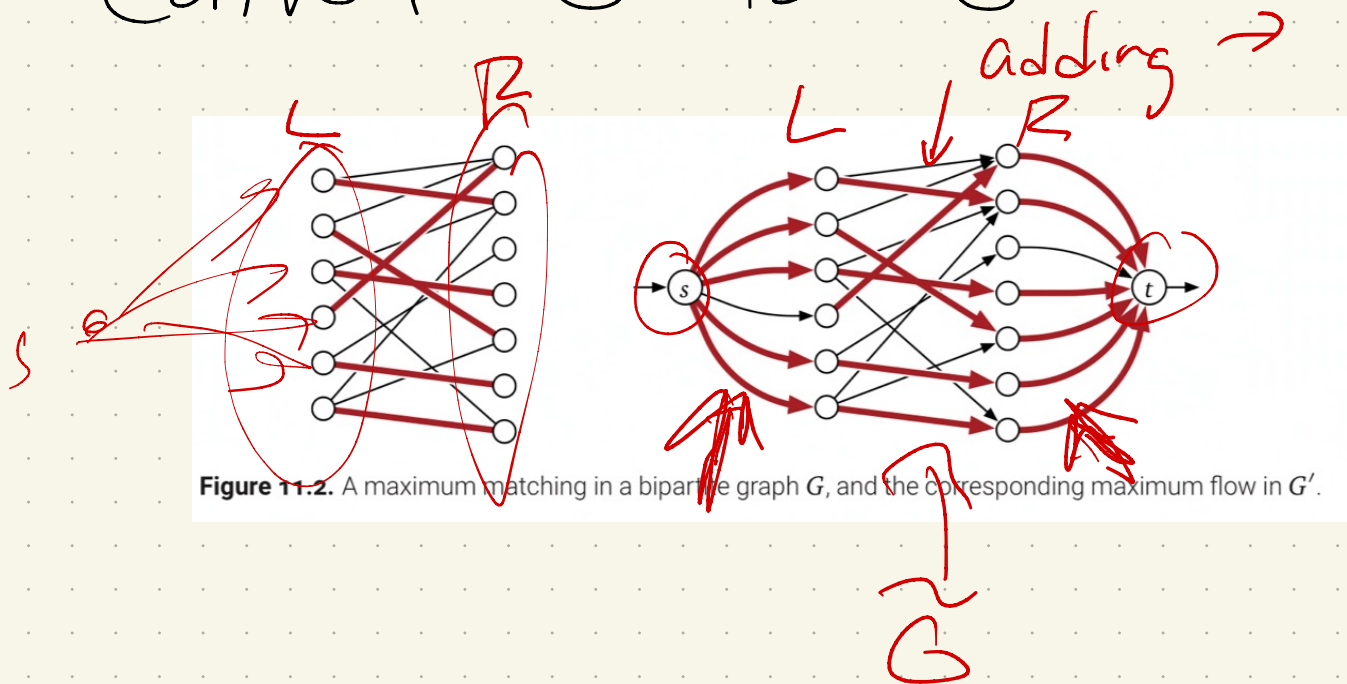
Given a (non-maximal) matching, how to improve?



remove
a-b from
matching
+ add 2 new edges
↳ size 4

Instead, use flows:

Convert G to $\tilde{G}$:



add $s \rightarrow t$

direct edges of G from
one set L to set R

add edges $s \rightarrow L$
(every vertex in L)

add edges from vertices in R
to t

give unit capacities to all
edges

Algorithm: Given $G = (V, E)$
with $V = L \cup R$ (bipartite)

// build $\tilde{G}$

add s & t

s 's adj list = L

add t to adj list of all $v \in R$
direct & give unit cap

// run flow

call $Orlin$

// get matching

trace flow paths, build
match that consists of
any $L \rightarrow R$ edge with $f(e) = 1$

Runtime: $O(\tilde{V} \tilde{E})$

$$= O((V+2)(E+V))$$

$$= O(V\tilde{E} + V^2) = O(V\tilde{E})$$

Correctness:

① Any matching in G
 $\Rightarrow$ flow in $\tilde{G}$

take matching edge $e = u \rightarrow v$

Set $f(e) = 1$

$\& f(s \rightarrow u) + f(v \rightarrow t) = 1$

valid, no capacity is too large

② Any flow in $\tilde{G} \Rightarrow$ matching
in G

flow decomposes into unit
paths, $s \rightarrow u \rightarrow v \rightarrow t$

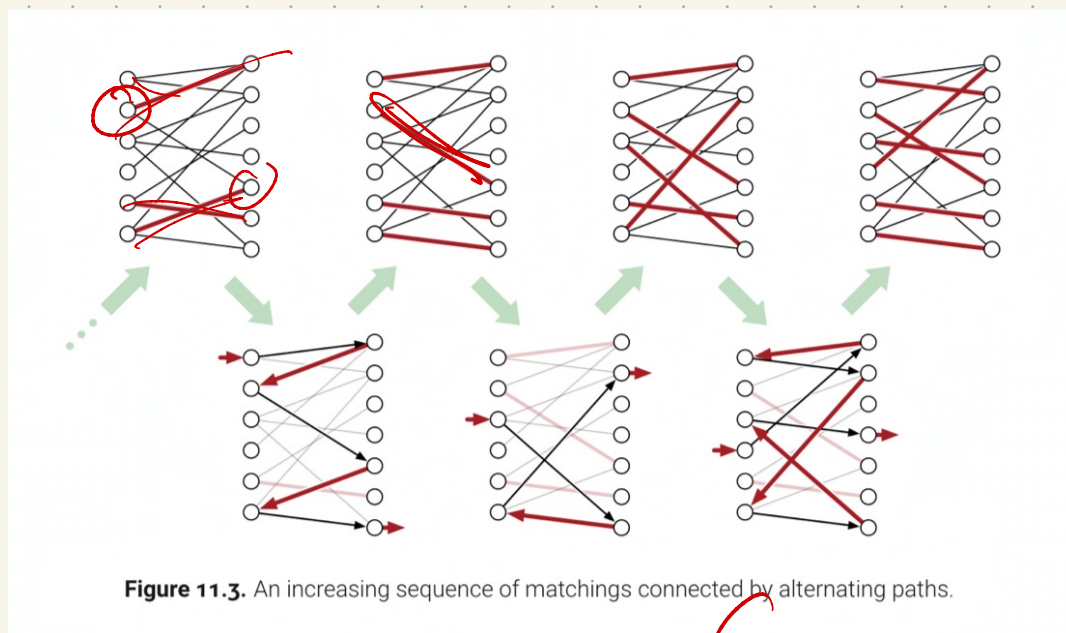
include $u \rightarrow v$ in matching

valid matching

therefore, max flow $\Leftrightarrow$ max
in $\tilde{G}$ matching
in G

Aside: How??

(FF is somehow improving matching...)



using G_f
this is our iterative
improvement idea

Crazier "word problem" examples

A company sells k products,
+ keeps records on customers.

Goal: Design a survey to send
to n customers, to
get feedback.

- Each customer's survey
shouldn't be too long,
+ should ask only about
products they purchased
- Each product needs
some # of reviews
from different customers

- Input:
- k products
 - n customers
 - records of who bought what: a_{ij} for $i \leq k, j \leq n$
 - For each customer,
 C_i is max # of products to ask them about
 - for each product, P_i is minimum # of reviews needed.

Can we design a survey?

Algorithm

Runtime $\leftrightarrow$ correctness